



## ICP Family Programmers: DLL Description

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## 1 Installation

### 1.1 Install "ICP for Windows"

Run "ICP for Windows" setup file "IcpWin\_setup\_xxx.exe". It can be obtained from supplied CD or downloaded from:

[http://softlog.com/index.asp?page=Downloads&parentid=5#ICP\\_Family\\_GUI\\_Software](http://softlog.com/index.asp?page=Downloads&parentid=5#ICP_Family_GUI_Software)

This manual presumes that you are familiar with "ICP for Windows" software

### 1.2 Install "ICP DLL"

Run DLL setup file "IcpDll\_setup\_dll\_xxx.exe". It can be obtained from supplied CD or downloaded from:

[http://www.softlog.com/index.asp?page=Downloads&parentid=5#ICP\\_Family\\_DLL\\_Software](http://www.softlog.com/index.asp?page=Downloads&parentid=5#ICP_Family_DLL_Software)

The following files will be installed to the default directory "C:\Program Files\Soft-Log\IcpDll":

###	File Name	Description
1.	IcpDll.dll	ICP DLL
2.	IcpWinComLine.exe	ICP Command line utility. See document "ICP Command Line.pdf" for details
3.	c_icpexp.h	Header file with ICP DLL functions
4.	fr_exp.h	Header file with ICP DLL definitions
5.	fr_icp2.h	Header file with ICP2 hardware definitions
6.	DLL Description.pdf	This document
7.	ICP Command Line.pdf	ICP Command line utility description
8.	ICP2 - FTM Functions.pdf	Description of ICP FTM (final test machine) functions
9.	\Lib_Borland\IcpDll.lib	LIB file for Borland C Builder
10.	\Lib_Microsoft\IcpDll.lib	LIB file for Microsoft C++
11.	\VB_Microsoft\c_icpexp.bas	Header file with ICP DLL functions for Microsoft Visual Basic

## 2 ICP Firmware Options

DLL/Command Line Support (D) should present in order to use DLL functions. Order Softlog programmers with "D" suffix, for example ICP2-D or ICP2GANG-D or activate "D" support remotely. For more details see page 2 of <http://softlog.com/userfiles/file/Downloads/Comparison.pdf> or contact Softlog Systems

Use the following sequence to validate your ICP firmware options:

- connect the programmer unit to the PC
- run "ICP for Windows"
- if programmer is connected and communication is OK then press "Details" button on "About" screen
- if incorrect COM is selected then open "Communication→RS-232/USB/Bluetooth COM", select the detected COM and press OK, then press "Details" as specified above

## 3 General Sequence of Operations

Step	Function	Description	Usage
1.	IcpStartApplication()	Starts ICP application	Should be called once before other ICP DLL functions can be called, <b>mandatory</b> . Next call can be only done after application is closed by IcpEndApplication()
2.	IcpInitCom()	Initializes COM port	Once, <b>mandatory</b> if communication is required. Next call can be done after COM is released by IcpReleaseCom()
3.	IcpLoadHexAndSerFile()	Loads hex and/or serialization files	Once or repeated, <b>mandatory in PC-driven</b> mode
4.	IcpDoAction()	Executes action according to ACTION_LIST	Once or repeated, not mandatory
5.	IcpReleaseCom()	Releases COM port	Once or repeated, not mandatory
6.	IcpEndApplication()	Closes the application	Once, <b>mandatory</b>

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## 4 Configuration File (\*.cfg)

Function `IcpStartApplication()` uses ICP configuration file ("icp01.cfg") as a parameter. The following procedure is recommended for preparing "icp01.cfg" file:

- Run "ICP for Windows" software
- Select programmer: "Programmer → Select Programmer"
- Select COM: "Communication → RS-232/USB/Bluetooth COM"
- Select device to be programmed: "Device → Select by Name"
- Set desired voltages, etc.: "Options → Voltages"
- Save configuration file: "File → Save Configuration"
- Validate that interactive programming works correctly
- Exit the software
- Copy "icp01.cfg" to your project directory and rename. NOTE: "icp01.cfg" is usually located in directory "C:\Program Files\Soft-Log\IcpWin"

## 5 Quick Start

- Install ICP DLL as described in chapter 1 to directory "C:\Program Files\Soft-Log\IcpDll"
- Prepare "icp01.cfg" file as described in chapter 4
- Create project directory, for example "**C:\MyProject**"
- Run Visual C++ and create a new project, for example **Project1**
- Copy ICP DLL files from "C:\Program Files\Soft-Log\IcpDll" as follows:
  - to "**C:\MyProject**":
    - "c\_icpexp.h"
    - "fr\_exp.h"
    - "IcpDll.lib" (from "C:\Program Files\Soft-Log\IcpDll\Lib\_Microsoft")
  - to "**C:\MyProject\Debug**":
    - Icp01.cfg
    - IcpDll.dll
- Define "IcpDll.lib" as a part of the project:
  - Visual Studio C++ 6.0:
    - select menu item "Project->Settings"
    - select tab Link
    - select mode "All Configurations" in combo box "Settings For"
    - fill field "Object/library modules" with string "IcpDll.lib"
    - press OK
  - Visual Studio C++ 2008:
    - select menu item "Project->Properties"
    - select tree items "Linker->Input"
    - select mode "All Configurations" in combo box "Configuration"
    - fill field "Additional Dependencies" with string "IcpDll.lib"
    - press OK
- Write a simple PC-driven application – see example in chapter 15.1
- Select **Debug** mode, compile and run the application
- After debugging is done copy files "Icp01.cfg" and "IcpDll.dll" from directory "**C:\MyProject\Debug**" to "**C:\MyProject\Release**"
- Select **Release** mode, compile and run the application

## 6 Base Functions

### 6.1 *IcpStartApplication*

**Description:** Starts application and loads configuration file  
**Prototype:** `int DLL_FUNC IcpStartApplication (char *aFileCfg)`  
**Parameters:** `aFileCfg` - ICP configuration file to be loaded, usually "icp01.cfg"  
**Example:** `int Stat = IcpStartApplication ("c:\MyProject\Icp01.cfg");`

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## 6.2 *IcpInitCom*

**Description:** Initializes RS-232/USB/Bluetooth COM port  
**Prototype:** int DLL\_FUNC IcpInitCom (int aOverCfg, int aComPort, int aBaudRate)  
**Parameters:** aOverCfg: 0-gets communication parameters from \*.cfg file  
1-overrides \*.cfg file with aPort and aBaudRate  
aPort: 0-COM1, 1-COM2,...  
aBaudRate: see enum BAUD\_RATES (file fr\_exp.h)  
**Example:** Stat = IcpInitCom( 0, 0, 0 ); //use settings from \*.cfg file

## 6.3 *IcpLoadHexAndSerFile*

**Description:** Loads HEX and serialization files  
**Prototype:** int DLL\_FUNC IcpLoadHexAndSerFile (char \*aFileHex, char \*aFileSer)  
**Parameters:** aFileHex - pointer to char string that contains HEX file name  
aFileSer - pointer to char string that contains serialization file name  
**Example 1:** Stat = IcpLoadHexAndSerFile ("c:\MyProject\1.hex", "c:\MyProject\1.ser");  
**Example 2:** Stat = IcpLoadHexAndSerFile ("c:\MyProject\1.hex", ""); //hex file only  
**Example 3:** Stat = IcpLoadHexAndSerFile ("", "c:\MyProject\1.ser"); //serialization file  
//only (standalone operation)

## 6.4 *IcpTestConnection*

**Description:** Description: communicates with the programmer as follows:  
- if ICP2 then with ICP2  
- if GANG then with channel 2  
- if GANG(single channel) then with the selected channel  
No LEDs are activated on the programmer (blind connection)  
**Prototype:** int DLL\_FUNC IcpTestConnection(void)  
**Parameters:** None  
**Example:** int err= IcpTestConnection();  
if (err != AUTO\_OK) //(see errorcodes in chapter 14)  
<means communication error>

## 6.5 *IcpDoAction*

**Description:** Executes programming, verification and other actions specified in enum ACTION\_LIST – see 14.2.1  
**Prototype:** int DLL\_FUNC IcpDoAction( int aAction,  
unsigned int aMemorySpace,  
unsigned int aPmUserRange,  
unsigned int aPmAddrBeg,  
unsigned int aPmAddrEnd,  
unsigned int aSaveResult,  
char\* aReadFile );  
**Parameters:** aAction: one of values of ACTION\_LIST. Note: ICP software automatically removes memory spaces which do not exist in the selected device  
aMemorySpace: sum of memory spaces - see MEMORY\_SPACES in 14.2.2

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aPmUserRange: 0-use full PM range,  
1-override with aPmAddrBeg and aPmAddrEnd

aPmAddrBeg: start address of PM (if aPmUserRange=1)  
aPmAddrEnd: end address of PM (if aPmUserRange=1)  
aSaveResult: 1-operation result will be written to file "auto01.res"  
aReadFile: hex file to be saved after read (if aAction=ACT\_READ)

**Example 1 (PC-driven mode):** Program (and verify) entire chip

```
int Stat = IcpDoAction( ACT_PROG,          //aAction
                      ALL_SPACE,        //aMemorySpace
                      0,                 //aPmUserRange
                      0,                 //aPmAddrBeg
                      0,                 //aPmAddrEnd
                      0,                 //aSaveResult
                      "");               //aReadFile
```

**Example 2 (PC-driven mode):** Verify locations 0x0020-0x003F of PM

```
Stat = IcpDoAction( ACT_VER,            //aAction
                   PM_SPACE,           //aMemorySpace
                   1,                  //aPmUserRange
                   0x0020,             //aPmAddrBeg
                   0x003F,             //aPmAddrEnd
                   0,                  //aSaveResult
                   "");               //aReadFile
```

**Example 3 (PC-driven mode):** Read entire chip to file "c:\prj\hex1.hex"

```
Stat = IcpDoAction( ACT_READ,          //aAction
                   ALL_SPACE,        //aMemorySpace
                   0,                 //aPmUserRange
                   0,                 //aPmAddrBeg
                   0,                 //aPmAddrEnd
                   0,                 //aSaveResult
                   "c:\prj\hex1.hex"); //aReadFile
```

**Example 4 (Standalone mode):** Program (and verify) all chip(s)

```
int Stat = IcpDoAction( ACT_STA_PROG,   //aAction
                      ALL_SPACE,        //aMemorySpace (Note 1)
                      0,                 //aPmUserRange
                      0,                 //aPmAddrBeg
                      0,                 //aPmAddrEnd
                      0,                 //aSaveResult
                      "");               //aReadFile
```

Note 1: aMemorySpace parameter does not affect standalone operation since memory space is selected according to environment settings saved in ICP2 internal flash memory

## 6.6 IcpReleaseCom

**Description:** Releases serial communication port  
**Prototype:** int DLL\_FUNC IcpReleaseCom (void)  
**Parameters:** None

**Example:** Stat = IcpReleaseCom();

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## 6.7 *IcpEndApplication*

**Description:** Terminates ICP DLL application  
**Prototype:** int DLL\_FUNC IcpEndApplication (void)  
**Parameters:** None

**Example:** Stat = IcpEndApplication();

## 6.8 *IcpReadDIIVersion*

**Description:** Gets DLL version string  
**Prototype:** int DLL\_FUNC IcpReadDIIVersion (char \*dllSoftwareVer)  
**Parameters:** dllSoftwareVer – pointer to DLL version string

**Example:** char DIIVersion[80];  
Stat = IcpReadDIIVersion (DIIVersion);

## 6.9 *IcpEnableProgressWindow*

**Description:** Enables/disables progress window (progress bar)  
**Prototype:** int DLL\_FUNC IcpEnableProgressWindow(int aEnable);  
**Parameters:** aEnable: 0-disable, 1-enable

## 6.10 *IcpDIISelectProg*

**Description:** Selects programmer type and mode by overwriting value from \*.cfg file, useful to switch between ICP2-GANG channels and standalone/PC-driven modes

**Prototype:** int DLL\_FUNC IcpDIISelectProg(int aProg, int aMode, int aCh)  
**Parameters:** aProg - programmer according to enum PROG\_TYPE – see 14.2.3  
aMode - mode of operation according to enum PROG\_MODE – see 14.2.3  
aCh - current channel for "GANG-single channel" programmer, 0 for channel 1

**Return Value:** A) AUTO\_OK if parameters are correct  
B) -1: parameter 1 is not correct  
-2: parameter 2 is not correct  
-3: parameter 3 is not correct

**Example:** Select channel 2 of ICP2-GANG programmer for PC-driven operation, then restore to GANG  
IcpDIISelectProg(PROG\_GANG4\_SINGLECHAN, SPM\_PCDRIVEN,1);  
... - execute desired PC-driven operations with channel 2  
IcpDIISelectProg(PROG\_GANG4, SPM\_STANDALONE, 0); //restore GANG standalone

# 7 Standalone Operation: General Functions

## 7.1 *IcpDoAction* – see 6.5

See IcpDoAction() with parameters ACT\_STA\_PROG, ACT\_STA\_GET\_RES and ACT\_STA\_START\_PROG

## 7.2 *IcpDIIGetInfoSingle*

```
enum INFO_ICP_OPTIONS {  
    INFO_OPT_DLL      = 0x0001, //1-DLL support enabled  
    INFO_OPT_DSPIC    = 0x0002, //1-dsPIC support enabled  
    INFO_OPT_KEE      = 0x0004, //1-Keeloq support enabled  
    INFO_OPT_SEC      = 0x0008, //1-security feature support enabled
```

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```
INFO_OPT_PIC32    = 0x0010 //1-PIC32 support enabled
};

#define INFO_ID_SIZE      3 //firmware ID length
#define INFO_GANG_QUAN   64 //maximum number of GANG channels

typedef struct //info from one channel of ICP2/ICP2-GANG
{
    int iValid;                //1-information in this structure is valid
    unsigned short iProgType;  //programmer type according to PROG_TYPE
    unsigned short iFirmVer;   //firmware version (H.L)
    unsigned char iIcpld[INFO_ID_SIZE]; //firmware ID (ICP serial number)
    unsigned short iBootVer;   //bootloader version (H.L)
    unsigned short iIcpOpt;    //ICP enabled options according to INFO_ICP_OPTIONS above
    unsigned short iFirmDevDb; //firmware device database version (H.L.)
    unsigned short iFirmPrjDb; //firmware project database version (H.L.)
    unsigned short iDIIDevDb;  //DLL device database version (H.L.)
    unsigned short iDIIPrjDb;  //DLL project database version (H.L.)

    int iSecMode;              //security mode (1-secure environment now)
    int iEnvStat;              //environment status according to enum PRJ_VAL – see 14.2.5
    char iEnvHexFileName[SEC_ID_SIZE]; //HEX file name inside the environment
    unsigned short iEnvHexFileCs; //HEX file checksum
    char iSecIdName[SEC_ID_SIZE]; //Security ID name
    int iSecCntValue;          //value of non-volatile security counter
    int iSecCntInteg;          //security counter integrity (0=OK)
} ICP_INFO;
```

**Description:** Get environment and ICP general info from a single channel

**Prototype:** int DLL\_FUNC IcpDIIGetInfoSingle(ICP\_INFO \*aInfo)

**Parameters:** aInfo - pointer to ICP\_INFO structure

**Example:** Validate that environment is OK and HEX file checksum is 0x1234

```
ICP_INFO MyInfo;
IcpDIIGetInfoSingle(&MyInfo);
if (! MyInfo.iValid) //invalid environment
    return 1;

if (MyInfo.iEnvHexFileCs != 0x1234)
    return 2;

return 0; //OK
```

## 7.3 IcpReadStaResOneCh

**Description:** Reads result of standalone operation for one channel. Should be called in loop for all channels after previous programming is done

**Prototype:** int DLL\_FUNC IcpReadStaResOneCh(unsigned int aCh);

**Parameters:** aCh: channel number, range 0...63. NOTE: aCh is 0 for ICP2 (not GANG)

**Return Value:** A) -1 if channel is not enabled  
B) -2 if channel number is out of range (>63)  
C) according to AUTO\_ERROR\_LEVEL

**Example:** Program 8 channels of ICP2-GANG and get results

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**Step 1:** Execute standalone programming for 8 channels

```
#define CH_NUM 8 //8 channels
int Res[CH_NUM];
int Stat = IcpDoAction( ACT_STA_PROG, //aAction
                      0, //aMemorySpace
                      0, //aPmUserRange
                      0, //aPmAddrBeg
                      0, //aPmAddrEnd
                      0, //aSaveResult
                      ""); //aReadFile
```

**Step 2:** Analyze result

```
if (Stat==AUTO_OK) {
    ; //do nothing, all channels OK
}
else {
    for (int i=0; i<CH_NUM; i++)
        Res[i]= IcpReadStaResOneCh[i]; //save all results
}
```

## 8 Standalone Operation: Create/Transfer Environment

Simultaneous GANG programming can be done in standalone mode only. An environment should be created and transferred to the programmer unit before programming takes place

An environment can be created and transferred by 3 methods:

- Off-line by using "ICP for Windows" ("Environment → Save Environment As" and "Environment → Transfer Environment to Programmer")
- On-line by using DLL functions below
- Combination of the both methods above, i.e. multiple environments can be created off-line and then transferred by DLL function

**IMPORTANT:** A transferred environment is saved in **non-volatile** flash memory of the programmer and automatically reloads after power-up. Don't transfer the same environment multiple times to keep endurance of internal ICP2 flash (10K cycles minimum, 100K typical)

### 8.1 IcpSaveEnvironment

**See also:** IcpTransferEnvironmentToIcp()

**Description:** Creates and saves current workspace into an environment file (extension \*.pj2)

**Prototype:** int DLL\_FUNC IcpSaveEnvironment (const char\* aFileName);

**Parameters:** aFileName - pointer to char string containing file name

**Example:**

```
IcpStartApplication ("icp01.cfg");
IcpInitCom (0, 0, 0);
IcpLoadHexAndSerFile("1.hex", "");
IcpSaveEnvironment ("File1.pj2");
IcpEndApplication();
```

### 8.2 IcpTransferEnvironmentToIcp

**See also:** IcpSaveEnvironment()

**Description:** Transfers an environment file (extension \*.pj2) to the programmer

**Prototype:** int DLL\_FUNC IcpTransferEnvironmentToIcp (const char\* aFileName);

**Parameters:** aFileName - pointer to char string containing file name





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**Return Value:** A) -1: incorrect parameter(s)  
B) according to AUTO\_ERROR\_LEVEL

**Example:** Validate that RAM buffer is loaded as expected

```
#define OVERWRITE_LEN 20 //20 bytes to be loaded
char MyBuf[] = "ICP2 Programmer";
char MyVerifyBuf[OVERWRITE_LEN];
IcpRamBufWrite(MyBuf, 0, OVERWRITE_LEN);
IcpRamBufRead(MyVerifyBuf, 0, OVERWRITE_LEN);
Compare MyBuf and MyVerifyBuf
```

## 10 Standalone Operation: Multiple Environments

Up to 2 environments can be loaded into a single channel of ICP2/ICP2-GANG. Default environment size is as follows:

- environment 1: 655KByte (may extend to 1MByte is environment 2 is not used)
- environment 2: 390Kbyte. This size is suitable for all devices excluding PIC32 with flash size 512Kbyte

Environment 1 is always selected after power-up for ICP2/ICP2-GANG

### 10.1 IcpSwitchEnv

**Description:** Communicates with programmer and simultaneously switches environment for all channels

**Prototype:** int DLL\_FUNC IcpSwitchEnv (int aEnv);

**Parameters:** aEnv should be 0 (environment 1) or 1 (environment 2)

**Return Value:** A) -1: environment number is out of range  
B) -2: operation is not supported (ICP-01)  
C) according to AUTO\_ERROR\_LEVEL

**Example:** IcpSwitchEnv(1); //switch to environment 1

## 11 PC-Driven Operation: Access to PC Memory Buffers

Function IcpGetBuffers() allows reading and modification of internal programming buffers in PC-driven mode. It may be useful for applications that require buffer manipulation without (or in addition to) using hex file.

NOTE: be careful when modifying programming buffers

### 11.1 IcpGetBuffers

```
typedef struct { //use members shown in bold italic
    int PmWordSize; // Program Memory word size
    unsigned PmMaxWordVal; // Program Memory maximal word value
    int PmAddrUnit; // Program Memory address unit
    char *PmBuf; int PmSize; // Program Memory (flash)
    char *IdBuf; int IdSize; // ID Memory
    char *DmBuf; int DmSize; // Data Memory (EEPROM)
    char *CmBuf; int CmSize; // Calibration Memory (not supported)
    char *FuBuf; int FuSize; // Fuses Memory (configuration words)
} iBUFFERS;
```

**Description:** Provides pointer to the internal programming buffers (in PC memory)

**Prototype:** void DLL\_FUNC IcpGetBuffers (iBUFFERS \*aBufs);

**Parameters:** pointer to structure iBUFFERS

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**Return Value:** none

**Example:**     iBUFFERS MyBuf;  
                  IcpGetBuffers(&MyBuf);  
                  MyBuf.DmBuf[1]=0x55; //modify buffer for EEPROM programming  
                  MyBuf.DmBuf[2]=0x56; //  
                  IcpDoAction(ACT\_PROG,...); //execute PC-driven programming

## 12 Direct Hardware Control

ICP DLL provides direct access to ICP2/ICP2-GANG hardware. The functions are listed below, for more details see document "ICP2 - FTM Functions.pdf"

###	Function Name	Function Description
1.	Icp2AdConv()	Execute A/D Conversion
2.	Icp2DaVolt ()	Set D/A Levels (not pins) for VDD, VPP or VLIM
3.	Icp2PinState()	Set/Read Pin State
4.	Icp2ClockDataComPar()	Set CLOCK/DATA ("RB6/RB7") Communication Parameters
5.	Icp2SingleClockDataAction()	Execute single CLOCK/DATA Communication
6.	Icp2MultiClockDataAction()	Execute multiple CLOCK/DATA Communications
7.	Icp2SafeOff()	Turn ICP2 pins to safe state (off)

## 13 More DLL Functions

File "c\_icpexp.h" contains many additional DLL functions (write/read to internal ICP EEPROM, calibration, security, FTB9 operation, etc). Specify your tasks and contact Softlog Systems for suggestion. Additional DLL functions can be done upon your request

## 14 Appendix A: Return Values and Definitions

### 14.1 Return Values

DLL functions return value according to enum AUTO\_ERROR\_LEVEL below:

```
enum AUTO_ERROR_LEVEL { //return values
AUTO_OK                = 0, //operation OK
AUTO_DB_ERR            = 1, //database error
AUTO_COM_ERR           = 2, //communication error
AUTO_VDD_ERR           = 3, //Vdd overload error
AUTO_VPP_ERR           = 4, //Vpp overload error
AUTO_HEX_ERR           = 5, //HEX file loading error
AUTO_SER_ERR           = 6, //serialization file error
AUTO_VER_ERR           = 7, //verification error
AUTO_ERR_NO_SPACE      = 8, //no space selected
AUTO_SAVE_ERR          = 9, //file save error
AUTO_SOCKET_ERR        = 10, //socket communication error (obsolete)
AUTO_I2C_ERR           = 11, //UUT I2C communication error
AUTO_DLL_ERR           = 12, //DLL programming is not supported
AUTO_KEY_ERR           = 13, //key generation error
AUTO_CFG_ERR           = 14, //config. file error
AUTO_COM_NUM_ERR       = 15, //invalid COM number
AUTO_COM_BUSY_ERR      = 16, //selected COM is busy
AUTO_COM_BAUD_ERR      = 17, //invalid baud rate
AUTO_COM_NO_OPEN       = 18, //can't open COM port
AUTO_USER_CANCEL       = 19, //user cancel
AUTO_IN_PROGRESS       = 20, //operation in progress
AUTO_BC_ERR            = 21, //blank check error
AUTO_OP_NOT_ALLOW      = 22, //operation not allowed for selected programmer
AUTO_FW_INVALID        = 23, //firmware invalid-firmware upgrade needed
AUTO_24LC_ADDR_ERR    = 24, //24LC01 address (offset) is out of range
AUTO_DM_ADDR_ERR       = 25, //DM range error
AUTO_FIRM_ERR          = 26, //firmware version error
AUTO_NO_SUB            = 27, //no ICP-SUB PCB
AUTO_NO_SUP_KEE        = 28, //no keeloq support
AUTO_NO_SUP_DSPIC      = 29, //no dsPIC support
```

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AUTO_ICP2_REQ	= 30, //ICP2 required
AUTO_DEV_ERR	= 31, //device selection error (unspecified error)
AUTO_PROG_MISMATCH	= 32, //mismatch between selected and detected programmers
AUTO_PRJ_INVALID	= 33, //Invalid environment
AUTO_PRJ_DB_FIRM_PC_MIS	= 34, //mismatch between PC and firmware database
AUTO_PRJ_DB_FIRM_AT45_MIS	= 35, //mismatch between environment and firmware database
AUTO_DLL_SUPPORT_REQUIRED	= 36, //obsolete: "GO" pressed on hardware and no DLL/standalone support
AUTO_PRJ_CS	= 37, //environment CS error
AUTO_STA_IDLE	= 38, //programmer is idle or standalone operation can't be started
AUTO_STA_BUSY	= 39, //standalone operation: programmer busy
AUTO_ENV_ERR	= 40, //environment file error
AUTO_PM_RANGE	= 41, //invalid PM range specified
AUTO_SEC_SUPPORT_REQUIRED	= 42, //Security support required
AUTO_SEC_CNT_INTEG	= 43, //Future: Security feature: integrity error in counter
AUTO_SEC_CNT_ZERO	= 44, //Future: Security feature: counter = 0
AUTO_SEC_NO_FUNC	= 45, //Future: Security feature: function does not exist
AUTO_SEC_PACK_ERR	= 46, //Future: Security feature: packet error
AUTO_SEC_EEPROM_FAIL	= 47, //Future: Security feature: EEPROM error
AUTO_SEC_ANTI_SCAN	= 48, //Future: Security feature: anti-scan activated,
AUTO_SEC_SEC_ID_CMP	= 49, //Future: Security feature: incorrect Security ID
AUTO_SEC_PASSW_CMP	= 50, //Future: Security feature: incorrect password
AUTO_SEC_BATCH_CMP	= 51, //Future: Security feature: incorrect batch
AUTO_SEC_VERS_ERR	= 52, //Future: Security feature: version error
AUTO_SEC_UNKNOWN_ERR	= 53, //Future: Security feature: unknown error
AUTO_NO_ROW_ERASE	= 54, //row erase is not supported
AUTO_INVALID_PARAM	= 55, //invalid parameters
AUTO_MOVLW_RETLW_CALIB	= 56, //no movlw in calibration word
AUTO_NO_USUAL_ENV_TRAN	= 57, //Usual environment can't be sent if a secure one inside
AUTO_SEC_BUF_START_ADDR	= 58, //sec. buf. properties error: incorrec start addr
AUTO_SEC_BUF_END_ADDR	= 59, //sec. buf. properties error: incorrect end addr
AUTO_SEC_BUF_PAGE_START	= 60, //sec. buf. properties error: incorrect page start
AUTO_SEC_BUF_PAGE_SIZE	= 61, //sec. buf. properties error: incorrect page size
AUTO_SEC_BUF_NOT_EVEN	= 62, //sec. buf. properties error: length not even
AUTO_SEC_BUF_NO_DM	= 63, //sec. buf. properties error: no DM in PIC
AUTO_SEC_BUF_LAST_PAGE	= 64, //sec. buf. properties error: last PM page can't be used
AUTO_SEC_BUF_NO_16BIT_SUP	= 65, //sec. buf. properties error: no Script 1 for 16-bit devices
AUTO_SEC_BUF_NOT_MODULO_3	= 66, //sec. buf. properties error: length not modulo 3
AUTO_SEC_EMPTY_MASK	= 67, //Security feature: empty mask for secure environment
AUTO_TEST_COM_NO_SUPPORT	= 68, //ICP2 test command not supported
AUTO_TEST_NACK	= 69, //ICP2 test command returns NACK
AUTO_NO_SUP_P32	= 70, //no PIC32 support
AUTO_PIC32_BUSY_OR_DAMAGED	= 71, //PIC32 is busy or damaged
AUTO_PIC32_CP_OR_DAMAGED	= 72, //PIC32 is code protected or damaged
AUTO_PIC32_PE_ANSWER	= 73, //PIC32 programming executive: no answer
AUTO_PIC32_PE_VERSION	= 74, //PIC32 programming executive: incorrect version
AUTO_SEC_BUF_NO_32BIT_SUP	= 75, //no security support for PIC32
AUTO_CNT_ZERO	= 76, //non-secure (low-endurance) counter is 0
AUTO_DEMO_ERR	= 101 }; //demo version

## 14.2 Definitions

### 14.2.1 Action List

```
enum ACTION_LIST {  
    ACT_PROG           = 1, //PC-driven programming  
    ACT_VER            = 2, //PC-driven verification  
    ACT_READ           = 3, //PC-driven read  
    ACT_BC             = 4, //PC-driven blank check  
  
    ACT_STA_PROG       = 5, //Standalone programming  
    ACT_STA_GET_RES    = 6, //Standalone: communicate and get latest results  
    ACT_STA_CLR_RES    = 7, //Standalone: communicate and clear all latest results  
    ACT_STA_START_PROG = 8, //Standalone: start standalone programming (NOTE: should be monitored then for completion)  
};
```

### 14.2.2 Memory Spaces (PC-driven Operation)

```
enum MEMORY_SPACES {  
    PM_SPACE           = 0x0001, //Program memory (flash)  
    ID_SPACE           = 0x0002, //ID locations  
    DM_SPACE           = 0x0004, //Data memory (EEPROM)  
    CM_SPACE           = 0x0008, //Calibration memory (not supported)  
    FU_SPACE           = 0x0010, //Configuration word  
    ALL_SPACE          = PM_SPACE | ID_SPACE | DM_SPACE | FU_SPACE, //all spaces  
};
```

# ICP Family DLL Description

---

```
LAST_SPACE          = 0x0020
};
```

## 14.2.3 Programmer Type and Mode

```
enum PROG_TYPE {
    PROG_ICP01          = 0, //ICP-01
    PROG_ICP2          = 1, //ICP2 or ICP2(HC)
    PROG_GANG4         = 2, //ICP2-GANG (multichannel)
    PROG_GANG4_SINGLECHAN = 3, //ICP2-GANG (single channel)
    PROG_PORTABLE      = 4, //ICP2-Portable
    PROG_LAST
};
```

```
enum PROG_MODE {
    SPM_PCDRIVEN      = 0, //PC-driven mode
    SPM_STANDALONE    = 1, //Standalone mode
    SPM_LAST
};
```

## 14.2.4 Usage of RAM Buffer

```
enum RAM_BUF_USAGE {
    RAM_BUF_NO        = 0, //not used (default)
    RAM_BUF_PM        = 1, //override PM
    RAM_BUF_DM        = 2, //override DM (EEPROM)
    RAM_BUF_PM_DM     = 3, //override PM and DM (128 per each, for future use)
    RAM_BUF_SEC_COM   = 4, //internal use only: security feature related communication between PC and ICP
};
```

## 14.2.5 Environment Status

```
enum PRJ_VAL {
    prjUNKNOWN        = 0, //unknown state (for PC only)
    prjLOADING        = 1, //environment loading/validation in progress
    prjINVALID        = 2, //invalid environment
    prjVALID          = 3, //valid environment
};
```

## 14.2.6 Additional Definitions

See files "fr\_exp.h" and "fr\_icp2.h" for more definitions

# 15 Appendix B: Software Examples

Contact Softlog Systems for more examples

## 15.1 Software Example: PC-Driven Mode, Single Channel

```
// This example shows how to use ICP2 in PC-driven mode
// Be sure that COM port and other settings in *.cfg file meet your hardware setup

#include "fr_exp.h"
#include "c_icpexp.h"

#define CFG_FILE      "icp01.cfg"
#define HEX_FILE      "hex1.hex"
#define SER_FILE      "ser1.ser"

#define MY_ACTION     ACT_PROG          //action = PC-driven programming
#define MEM_SPACE     ALL_SPACE        //selected operation will apply to all memory spaces

#define PM_USER       0                //0-full PM range, 1-user defined
#define PM_START      0                //not valid if PM_USER=0
#define PM_END        0                //not valid if PM_USER=0

#define DM_USER       1                //1-user defined DM (EEPROM) range
#define DM_START      0                //DM start
#define DM_END        0x3F            //DM end

int FullCycle(void)
{
    int ret; //errorcode
```

# ICP Family DLL Description

---

```
ret = IcpStartApplication (CFG_FILE);
if(ret)
    return ret;

ret = IcpInitCom (0, 0, 0); //init COM from *.cfg file
if(ret) {
    IcpEndApplication();
    return ret;
}

//At this point application and USB/RS-232 COM port are successfully open

//Load HEX and serialization (SQTP) files (SQTP file is optional, define it as "" if not required)
//-----
ret = IcpLoadHexAndSerFile (HEX_FILE, SER_FILE);
if(ret) {
    IcpEndApplication(); //it also closes opened COM
    return ret;
}

//Enable progress window (optional)
//-----
IcpEnableProgressWindow (1);

//Maximize speed of PC operation (optional)
//-----
IcpSetSleepOnWaitingRS232(0); //no sleep

//Set DM (EEPROM) memory range (optional)
//-----
IcpSetDmRange (DM_USER, DM_START, DM_END);

//Execute programming - this operation can be done several times
//-----
ret = IcpDoAction ( MY_ACTION,
                   MEM_SPACE,
                   PM_USER,
                   PM_START,
                   PM_END,
                   0,
                   "");
}
IcpEndApplication();
return ret;
}
```

## 15.2 Software Example: Standalone Mode, Gang Programming

/\* This example shows how to use ICP2-GANG:

1) One-time operation: validate that environments inside ICP2-GANG channels are OK, otherwise transfer desired environment to the non-volatile memory of the programmer  
IMPORTANT: transfer environment as less as possible to keep endurance of internal ICP2 flash (10K cycles minimum, 100K typical)

2) Multiple operation: GANG programming

Be sure that COM port and other settings in \*.cfg file meet your hardware setup

\*/

```
#include "fr_exp.h"
#include "c_icpexp.h"

#define CFG_FILE          "icp01.cfg"
#define CHANNEL_QUAN     4          //4 GANG channels

unsigned short MyChecksum = 0xA882; //example
char MyEnvFile[] = "MyEnv.pj2"; //example
int Res[CHANNEL_QUAN]; //programming results for all GANG channels

int FullCycle(void)
{
    int ret;
    ret = IcpStartApplication (CFG_FILE);
    if(ret)
        return ret;

    ret = IcpInitCom (0, 0, 0); //init COM from *.cfg file
    if(ret) {
```

# ICP Family DLL Description

---

```
IcpEndApplication();
return ret;
}
//At this point application and USB/RS-232 COM port are successfully open

//Validate that all channels contain correct environment
//-----
ret=ValidateEnvironments(); //see function below
Sleep(1000); //delay should be at least 1 sec due to internal "dispatcher" delay in ICP firmware

//Execute programming - this operation can be done several times
//-----
if (! ret) {
    ret=ProgramGang();//see function below
    //<Analyze Res[]
}
IcpEndApplication();
return ret;
}

// Validate that all channels contain correct environment
// (**only after selection of new project/product**)
// =====
int ValidateEnvironments(void)
{
int ch_i;
int err;
int update_env;
ICP_INFO ChannelInfo;

IcpEnableProgressWindow(0); //disable progress window (can be enabled if you wish)
for (ch_i=0; ch_i<CHANNEL_QUAN; ch_i++) //channel-by-channel
{
    //Step 1.1: select GANG single channel + PC-driven
    //-----
    IcpDllSelectProg(PROG_GANG4_SINGLECHAN, SPM_PCDRIVEN, ch_i);

    //Step 1.2: Read environment info from a selected channel
    //-----
    err = IcpDllGetInfoSingle(&ChannelInfo);
    //<analyze err>

    update_env=0; //prepare
    if (ChannelInfo.iValid) //valid structure
    {
        if (ChannelInfo.iEnvStat==prjINVALID) //invalid environment
            update_env=1;
        else if (ChannelInfo.iEnvHexFileCs != MyChecksum) //incorrect HEX checksum
            update_env=1;
        //additional analysis can be added here
    }
    if (update_env) //environment to be updated
    {
        //Transfer environment
        //-----
        IcpEnableProgressWindow(1); //enable progress window
        err = IcpTransferEnvironmentToIcp(MyEnvFile); //transfer environment
        //<analyze err>
        IcpEnableProgressWindow(0); //disable progress window
    }
}
return err;
}

// GANG Programming
// =====
int ProgramGang(void)
{
int ch_i;
int err;

// Step 1: select programmer as GANG + standalone
// -----
IcpDllSelectProg(PROG_GANG4, SPM_STANDALONE, 0);

// Step 2: execute programming
// -----
```

# ICP Family DLL Description

---

```
IcpEnableProgressWindow (1);//enable progress window (optional)
err=IcpDoAction(
    ACT_STA_PROG, //aAction
    0,            //aMemorySpace (does nothing in standalone programming)
    0,            //aPmUserRange (does nothing in standalone programming)
    0,            //aPmAddrBeg   (does nothing in standalone programming)
    0,            //aPmAddrEnd   (does nothing in standalone programming)
    0,            //aSaveResult
    "");         //aReadFile

IcpEnableProgressWindow (0);//disable progress window

//Step 2.3: Analyze result
//-----
if (err==AUTO_OK)
{
    ; //do nothing, all channels OK
}
else
{
    for (ch_i=0; ch_i<CHANNEL_QUAN; ch_i++)
        Res[ch_i]=IcpReadStaResOneCh(ch_i); //read and save all results
}
return err;
}
```

## 15.3 More Software Examples

Contact Softlog Systems for more software examples (GANG programming with RAM buffer, other PC operations during programming, final test functions, etc)



# ICP Family DLL Description

---

## 16 Technical Assistance

You may contact Softlog Systems for technical assistance by calling, sending a fax or e-mail. To help us give you quick and accurate assistance, please provide the following information:

- Software version number, firmware version number and product serial number (if available). This information is displayed at the program start
- Detailed description of the problem you are experiencing
- Error messages (if any)
- Microcontroller part number (if device-related)
- Send us your "icp01.cfg" file

## 17 Warranty

Softlog Systems (2006) Ltd. warrants this product against defects in materials and workmanship for a period of 1 (one) year. This warranty will not cover programmers that, in the opinion of Softlog Systems, have been damaged due to abuse, improper use, disassembly, replacement of parts or attempted repair by anyone other than an authorized Softlog Systems service technician.

This product must be returned to the supplier for warranty service within the stated period. The buyer shall pay all shipping costs and other charges or assessments for the product by the supplier.

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## 18 Contact

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